

Assessing the accuracy of cosmological parameters estimated from velocity – density comparisons via simulations

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ABSTRACT

A promising method for measuring the cosmological parameter combination $f\sigma_8$ is to compare observed peculiar velocities with peculiar velocities predicted from a galaxy density field using perturbation theory. We use N -body simulations and semi-analytical galaxy formation models to quantify the accuracy and precision of this method. Specifically, we examine a number of technical aspects, including the optimal smoothing length applied to the density field, the use of dark matter haloes or galaxies as tracers of the density field, the effect of noise in the halo mass estimates or in the stellar-to-halo mass relation, and the effect of finite survey volumes. We find that for a Gaussian smoothing of $4 h^{-1}$ Mpc, the method has only small systematic biases at the level of 5 per cent. Cosmic variance affects current measurements at the 5 per cent level due to the volume of current redshift data sets.

Key words: galaxies: kinematics and dynamics – galaxies: statistics – cosmology: large-scale structure of Universe – cosmology: observations.

1 INTRODUCTION

Peculiar velocities are the only practical way of measuring the underlying distribution of dark matter (DM) on large scales (Willick et al. 1997), in the nearby (low-redshift) Universe. Specifically, they can be used to measure the cosmological parameter combination $f(\Omega_m)\sigma_8$, where the first term is the logarithmic growth rate of fluctuations, with $f(\Omega_m) = \Omega_m^{0.55}$ in the Lambda cold dark matter (Λ CDM) model, and σ_8 is the root mean square matter density fluctuation in a sphere of radius $8 h^{-1}$ Mpc. Although peculiar velocities have been used for similar purposes since the early 90s (see reviews by Dekel 1994; Strauss & Willick 1995), there has been a recent revival of interest in measuring $f\sigma_8$ (Pike & Hudson 2005; Davis et al. 2011; Hudson & Turnbull 2012; Turnbull et al. 2012; Carrick et al. 2015; Huterer et al. 2017; Dupuy, Courtois & Kubik 2019; Qin, Howlett & Staveley-Smith 2019; Adams & Blake 2020; Boruah, Hudson & Lavaux 2020; Said et al. 2020).

The use of peculiar velocities as a probe of $f\sigma_8$ has taken on renewed importance in light of the 3.2σ conflict between cosmic microwave background (Planck Collaboration VI 2018) and weak lensing measurements (Asgari et al. 2019) of the parameter combination $S_8 \equiv \Omega_m^{0.5}\sigma_8$, with the latter giving lower values. This combination is very similar to $f\sigma_8$, differing by only 0.05 in the exponent of Ω_m . As shown by Boruah et al. (2020), some recent peculiar velocity measurements also yield lower values of S_8 than Planck (as do most other probes of this parameter combination).

One method for measuring $f\sigma_8$ involves regressing the observed peculiar velocities (from e.g. supernovae, Tully–Fisher, or Funda-

mental Plane standard candles/rulers) on their predicted peculiar velocities from the density field of galaxies, obtained from a redshift survey. Specifically, the slope of this regression, β_g , is then combined with a measurement of the fluctuations of galaxies, $\sigma_{8,g}$ to yield an estimate of

$$f\sigma_8 = \beta_g \sigma_{8,g}, \quad (1)$$

as first suggested by Pike & Hudson (2005). The background theory and assumptions implicit in this method are discussed in more detail in Section 2.

The goal of this paper is to test the accuracy and precision of this method using large cosmological N -body simulations at a redshift of zero of DM haloes as a proxy for galaxies, as well as semi-analytical models of galaxy formation. Our approach is not to simulate all the observational properties of the surveys simultaneously (as in, for example, Nusser, Davis & Branchini 2014), but rather to consider one by one the different physical effects that may bias or add uncertainty to our results. In this sense, the paper is similar in spirit to Berlind, Narayanan & Weinberg (2000).

This paper is organized as follows. Section 2 describes the theoretical framework of the relationship between peculiar velocities and the density fluctuation field from linear perturbation theory, and the relevant cosmological parameters. Section 3 presents the simulation data and semi-analytical models that are used for the analyses performed in this paper. Section 4 describes the prescription for how we predict peculiar velocities. In Section 5, we investigate how the choice of smoothing kernel impacts our estimates of β/f and the amount of scatter generated in velocity–density cross-correlations. Section 6 investigates how uncertainties corresponding to 0.1 and 0.2 dex in halo mass measurements influence the predictions of β/f and

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$\sigma_{8,h}$. In Section 7, we instead explore how using either the stellar-to-halo mass relation (SHMR) or galaxy observables to weigh the density field impacts these cosmological estimates. Section 8 focuses on how these estimates are affected by volume limited surveys. Finally, Section 9 presents our conclusions.

2 PECULIAR VELOCITIES FROM LINEAR PERTURBATION THEORY

In linear perturbation theory, it is possible to relate the density field to the peculiar velocities of the galaxies at low redshift using

$$\mathbf{v}(\mathbf{r}) = \frac{H_0 f(\Omega_m)}{4\pi} \int \delta(\mathbf{r}') \frac{(\mathbf{r}' - \mathbf{r})}{|\mathbf{r}' - \mathbf{r}|^3} d^3 \mathbf{r}', \quad (2)$$

where $\mathbf{v}(\mathbf{r})$ is the peculiar velocity field and $\delta(\mathbf{r})$ is the matter density fluctuation field given by

$$\delta(\mathbf{r}) = \frac{\rho(\mathbf{r}) - \bar{\rho}}{\bar{\rho}}, \quad (3)$$

where $\rho(\mathbf{r})$ is the matter density field and $\bar{\rho}$ is its cosmic average. This calculation is only valid in the linear regime, where $\delta \lesssim 1$, allowing higher order terms to be ignored (Peebles 1993). For example, it does not predict the transverse components of a galaxy within a galaxy group. In Λ CDM, the rms matter density in spheres increases with decreasing sphere radius, so we expect linear theory to break down on small scales. In practice then, to apply equation (4) one needs to smooth $\delta(\mathbf{r})$.

In the linear regime, the density modes in Fourier space grow independently of one another. As a result it is easier to write equation (2) in Fourier space as follows:

$$\mathbf{v}_k = i H_0 f \frac{\mathbf{k}}{|\mathbf{k}|^2} \delta_k, \quad (4)$$

where H is the Hubble constant ($H = 100 h \text{ km s}^{-1} \text{ Mpc}^{-1}$). The smoothing is also simpler in Fourier space, because a convolution is a multiplication in Fourier space.

The density fluctuation field used in the previous equations is that of the underlying matter density field. Because it is dominated by DM, this cannot be measured empirically. Instead, an assumption must be made as to how the observed galaxies trace the underlying total matter. If one assumes linear biasing, the relation is

$$\delta_g = b_g \delta, \quad (5)$$

where b_g is the linear bias and δ_g is the density fluctuation field of the *galaxies*. Under this assumption, equation (2) can be written as

$$\mathbf{v}(\mathbf{r}) = \frac{H_0 f(\Omega_m)}{4\pi b_g} \int \delta_g(\mathbf{r}') \frac{(\mathbf{r}' - \mathbf{r})}{|\mathbf{r}' - \mathbf{r}|^3} d^3 \mathbf{r}'. \quad (6)$$

Note that if we express distances \mathbf{r} in units of $h^{-1} \text{ Mpc}$ (or km s^{-1}), as are naturally obtained from redshift surveys, then one must set $H = 100 \text{ km s}^{-1} \text{ Mpc}^{-1}$ (or 1, respectively) in the above expression. Thus when applying this equation to density fields derived from redshift surveys, the predictions are independent of the true value of H . The other two values outside the integral can be compacted into the parameter combination

$$\beta_g \equiv \frac{f}{b_g}. \quad (7)$$

If linear biasing holds, then $\sigma_{8,g} = b_g \sigma_8$. Putting this into equation (7), we find that the product of the observables to be $\beta_g \sigma_{8,g}$, as in equation (1), and so we can set constraints on cosmological parameters.

In reality, the assumptions of linearity, both in the context of perturbation theory and in the context of biasing, will not hold exactly. Fortunately, peculiar velocities are primarily generated by large-scale waves, where linearity will be a good approximation. Nevertheless, they also have a contribution from smaller, less linear scales. For these reasons, simulations are needed to calibrate any biases arising from non-linearities.

3 SIMULATION DATA

We use two publicly available simulations: Bolshoi and MultiDark Planck 2 (MDPL2; Klypin, Trujillo-Gomez & Primack 2011; Klypin et al. 2016), along with two simulated semi-analytical catalogues, SAG (Cora et al. 2018) and SAGE (Croton et al. 2016) which populate the DM haloes of MDPL2. We use the snapshots at $z = 0$. The halo and galaxy catalogues were obtained from the COSMOSIM data base.¹

The high-resolution Bolshoi simulation (Klypin et al. 2011) follows 2048³ particles in a comoving, periodic cube of length 250 $h^{-1} \text{ Mpc}$ from $z = 80$ to today. It has a mass and force resolution of $1.35 \times 10^8 h^{-1} M_\odot$ and 1 $h^{-1} \text{ kpc}$, respectively, and the DM haloes range from the masses of Milky Way satellites ($10^{10} M_\odot$) to the largest of clusters ($10^{15} M_\odot$). It was run as a collisionless DM simulation with the ADAPTIVE REFINEMENT TREE code (ART; Kravtsov, Klypin & Khokhlov 1997) and assumes a flat, WMAP5 cosmology with parameters $\Omega_m = 0.27$, $\Omega_\Lambda = 0.73$, $h = 0.7$, (linear) $\sigma_8 = 0.82$, and $n_s = 0.95$. Haloes in Bolshoi were identified using ROCKSTAR (Behroozi, Wechsler & Wu 2013a). The (non-linear) $\sigma_{8,m}$, measured from the particles is 0.897.

The MultiDark project consists of a suite of cosmological hydrodynamical simulations (Klypin et al. 2016), all assume a flat Λ CDM cosmology with cosmological parameters: $\Omega_m = 0.307115$, $\Omega_\Lambda = 0.692885$, $h = 0.6777$, linear $\sigma_8 = 0.8228$, and $n_s = 0.96$, that is consistent with Planck results (Planck Collaboration 2018). We focus on the MDPL2 simulation that has a periodic box of length 1000 $h^{-1} \text{ Mpc}$ evolved from a redshift of 120 to 0 with a varying physical force resolution level from 13 to 5 $h^{-1} \text{ kpc}$ and various implemented physics. The simulation uses 3840³ DM particles of mass $1.51 \times 10^9 h^{-1} M_\odot$, and has identified more than 10^8 haloes using ROCKSTAR (Behroozi et al. 2013a), with merger trees that were generated using CONSISTENT TREES (Behroozi et al. 2013b). The (non-linear) $\sigma_{8,m}$, measured from the particles is 0.95.

The SAG (Cora et al. 2018) and SAGE (Croton et al. 2016) semi-analytical models include the most relevant physical processes in galaxy formation and evolution, such as radiative cooling, star formation, chemical enrichment, supernova feedback and winds, disc instabilities, starbursts, and galaxy mergers. These models were calibrated to generate galaxy catalogues using the MDPL2 simulation. A comprehensive review of the models can be found in Knebe et al. (2017).

4 TESTING METHODS WITH N-BODY SIMULATIONS

Our goal is to test equation (6) using data from N -body simulations. Specifically, we will calculate the predicted peculiar velocities by integrating over a smoothed density tracer field, denoted by the

¹www.cosmosim.org

subscript ‘ t ’, used in place of $\delta_g(\mathbf{r})$ in the integral,

$$\mathbf{v}_{\text{pred}}(\mathbf{r}) = \frac{H_0}{4\pi} \int \delta_t(\mathbf{r}') \frac{(\mathbf{r}' - \mathbf{r})}{|\mathbf{r}' - \mathbf{r}|^3} d^3\mathbf{r}', \quad (8)$$

and compare this to the ‘observed’ (unsmoothed) velocity tracers, which are used in place of $\mathbf{v}(\mathbf{r})$ on the left-hand side of equation (6). Note that equation (8) omits the β_t term, which we fit to the N -body data by performing a linear regression

$$\mathbf{v}_t = \beta_t \mathbf{v}_{\text{pred}}, \quad (9)$$

where \mathbf{v}_t is the measured N -body velocity of a tracer of the velocity field which, in principle, need not be the tracer as used for the density field. This is a cross-correlation between two samples, and we will refer to it generically as a velocity–density cross-correlation, although the actual comparison is made between observed and predicted peculiar velocities.

The procedure used to obtain the density tracer field is the same regardless of whether the tracer data are particles, DM haloes or galaxies, as each simulation provides Cartesian positions and velocities for all tracers. The latter two also provide additional information such as halo mass, stellar mass, and luminosity measurements in different filter bands. In this paper, we will construct the density fluctuation field using all of the aforementioned tracers. In the following section, however, we will focus solely on using the particles for the density field.

Likewise, one also has a choice of which velocity tracers to use in the comparison. Using the particles as the velocity tracers is the most straightforward, so we will begin with this case in Section 5.1. Generally, however, observers usually combine the peculiar velocities from multiple galaxies in the same group or cluster to obtain the mean peculiar velocity of the group. The N -body analogue for the group-averaged peculiar velocity is the peculiar velocity of the host (or central) halo.

In order to calculate the density field, the density tracers are placed on a 3D cubic grid at the nearest grid point and the contribution of all tracers at the same grid point is summed.

In the case where grid spacing is non-negligible, the gridding acts like smoothing, and it adds in quadrature with the applied to yield a total effective smoothing (Boruah et al. 2020),

$$\sigma_{\text{total}}^2 = \sigma_{\text{grid}}^2 + \sigma_{\text{smooth}}^2, \quad (10)$$

where $\sigma_{\text{grid}}^2 = \frac{\Delta_{\text{grid}}^2}{12}$, where Δ_{grid} is the grid spacing in h^{-1} Mpc.

Using a fine grid allows us to preserve some of the detail and ignore the effects of grid size smoothing. All comparisons in this paper are done assuming a grid spacing of 0.36 and 0.98 h^{-1} Mpc for Bolshoi and MDPL2, respectively, which produces a negligible effect on the effective smoothing scales that will be used in this paper.

We choose to smooth the density fluctuation field using a Gaussian smoothing kernel, which, in configuration and Fourier space, are given by

$$W(\mathbf{r}) = \frac{1}{\sqrt{2\pi} R_G} \exp\left(\frac{-r^2}{2R_G^2}\right) \quad (11)$$

$$W(\mathbf{k}) = \exp\left(\frac{-k^2 R_G^2}{2}\right), \quad (12)$$

respectively. We then calculate the peculiar velocities on the 3D grid using equation (4). To predict the peculiar velocity of a given velocity tracer, we linearly interpolate from the velocity grid to the tracer’s location.

As discussed above, we then regress the tracer velocity against its predicted velocity, with the intercept fixed to zero, and where the

fitted slope gives an estimate for β_t . The fits also yield the rms (1D) velocity scatter, σ_v , of the difference between the N -body velocities and the linear theory predictions at the best fit β_t .

5 THE EFFECT OF SMOOTHING LENGTH ON THE ESTIMATED COSMOLOGICAL PARAMETERS

As discussed above, the density tracer field must be smoothed in order to predict the peculiar velocities in linear perturbation theory. In this section, we assess the impact of different Gaussian smoothing lengths on the recovered value of β_t , and the 1D σ_v around the linear theory predictions. We focus on smoothing scales between 1 and 6 h^{-1} Mpc.

Specifically, we aim to confirm at what smoothing length the slope of linear regression is unbiased, which previous work has suggested lies in the range 4–5 h^{-1} Mpc (Carrick et al. 2015). We first consider particles as tracers of the density field, and then consider haloes.

5.1 Particle-weighted density fluctuation field

We now consider the case in which we predict the peculiar velocities of particles using the particle density fluctuation field. The values of the best-fitting slope divided by the value of f in the simulation, i.e. β/f , as a function of smoothing scale, are shown in Fig. 1. This quantity should be unity if the method is unbiased. We find that predictions are unbiased for a Gaussian smoothing kernel R_G between 4 and 5 h^{-1} Mpc. Of the two simulations, MDPL2 should be more accurate since its minimum wavenumber k is $2\pi \times 10^{-3} h \text{Mpc}^{-1}$, and whereas that of Bolshoi is a factor 4 larger due to its smaller box length. Thus Bolshoi fails to capture the long-wavelength modes that generate a significant fraction of the rms peculiar velocity. The 1D σ_v around the best-fitting slope, however, is minimized at a smoothing length that is 1–1.5 h^{-1} Mpc smaller. The σ_v of particle peculiar velocities is high: between 225 and 275 km s^{-1} . This is because the particle’s peculiar velocity includes its motion within the halo as well as the peculiar velocity of the halo itself. Only the latter is well predicted by linear perturbation theory.

If we predict the peculiar velocities of host (or central) haloes (i.e. excluding subhaloes) using the particle density field, we find similar results, with unbiased results and minimum σ_v occurring for Gaussian smoothing lengths that are $\sim 0.5 h^{-1}$ Mpc smaller than when using particles as velocity tracers. The σ_v as a function of smoothing length is quite flat; it is not much higher at the fiducial 4 h^{-1} Mpc. However, the amplitude of σ_v for host haloes is significantly lower ($\sim 150 \text{ km s}^{-1}$) than for particles ($\sim 250 \text{ km s}^{-1}$), as expected given that the velocities of the particles include their motion with respect to the host halo.

Finally, it is interesting to explore the question of whether haloes of different masses have different velocities relative to the predictions of linear theory, one scenario of ‘velocity bias’. We find that imposing a minimum mass threshold on the haloes used to sample the velocity field of $10^{12} M_\odot$ has little effect on the measured β/f for smoothing lengths greater than 1.5 h^{-1} Mpc for MDPL2 and 3 h^{-1} Mpc for Bolshoi, as shown in Fig. 2. This is also true for a minimum mass of $10^{13} M_\odot$. A small velocity bias appears only when considering cluster mass haloes ($> 10^{14} M_\odot$) as peculiar velocity tracers. For clusters, there is also an increase in the 1D σ_v with respect to the linear theory predictions.

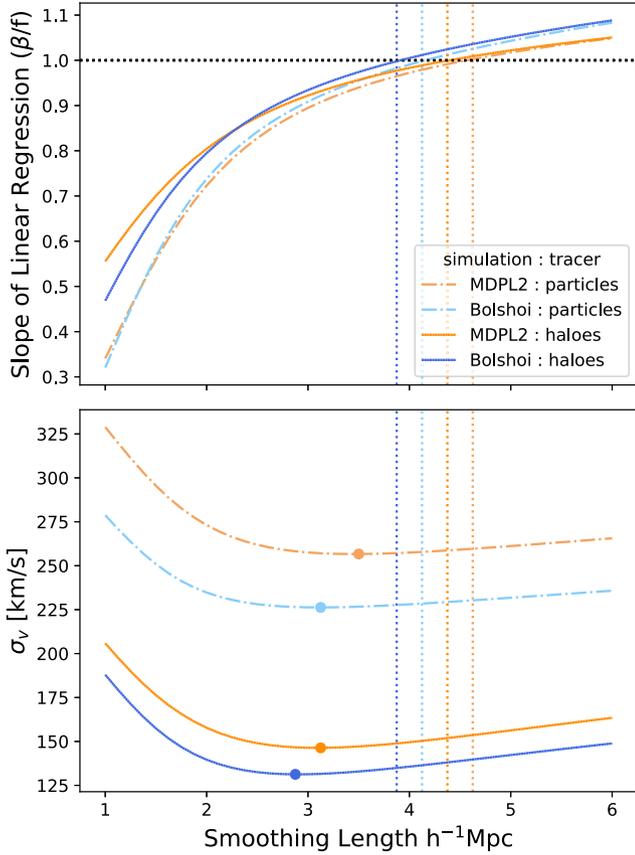


Figure 1. Top panel: Slope of linear regression for the predicted and N -body particle and central halo velocities (excluding subhaloes) for MDPL2 and Bolshoi simulations. Because we correct for the f parameter, a value of β/f of unity indicates for the smoothing length for which the velocity–density cross-correlation is unbiased. The predicted velocities were calculated assuming an underlying *particle* density field and linear theory for the Gaussian smoothing radius shown on the horizontal axis. Bottom panel: The scatter between the measured N -body and predicted peculiar velocity associated with each of the linear regression slopes. A circle has been placed at the smoothing length where the standard deviation was minimized.

5.2 Halo mass weighted density field

We now consider a scenario that is closer to the observational one, where the density field is provided by DM haloes, weighted by their mass. Whereas the particle density field is unbiased, this field will be biased. Therefore, we no longer expect $\beta_h/f = 1$. As discussed above, in the linear regime, this bias can be calculated by measuring the rms density fluctuations of the halo-weighted density field in $8 h^{-1}$ Mpc spheres. The halo and particle σ_8 measurements are related by

$$b_h = \frac{\sigma_{8,h}}{\sigma_{8,m}} \quad (13)$$

which is the same b in the β term defined previously. We measure β/f from the slope of linear regression as before, but multiplying this by the correction factor b_h . This should return a value of unity if the method is unbiased. This parameter combination will be referred to as $\beta^* = \frac{\beta}{f} \frac{\sigma_{8,h}}{\sigma_{8,m}}$.

To measure σ_8 , we place non-overlapping spheres of $8 h^{-1}$ Mpc covering the entire density field, and measure the standard deviation in the values. Doing this, we find values of $\sigma_{8,h} = 1.45 \pm 0.04$ and 1.57 ± 0.02 for the halo masses for Bolshoi and MDPL2, respectively,

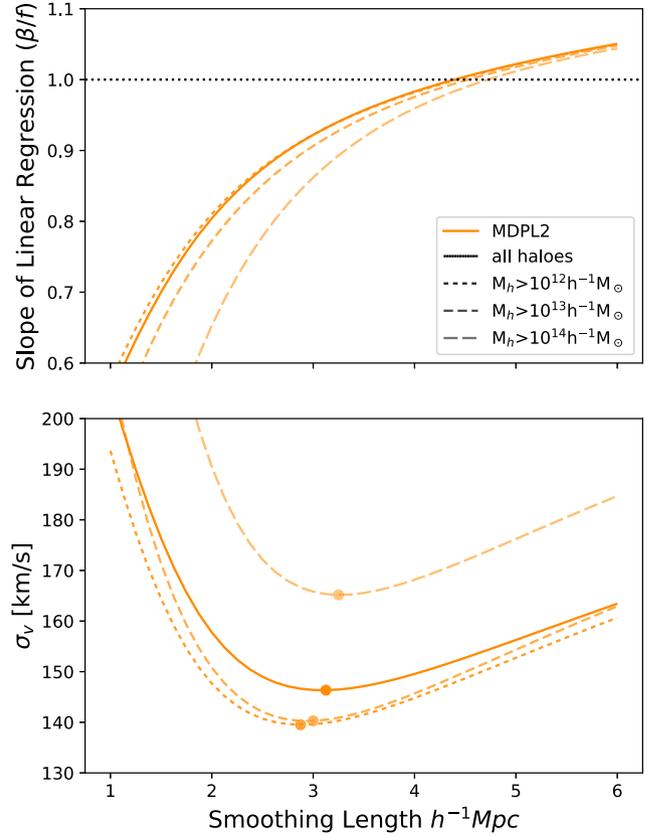


Figure 2. As in Fig. 1 where again the predicted peculiar velocities are based on the particle density field, but here these are compared to the N -body peculiar velocities of *haloes* (but excluding subhaloes). For clarity, the solid line labelled ‘all haloes’ represents all simulation objects classified as centrals, while the dashed lines represent centrals with masses greater than various minimum masses as indicated in the legend.

much larger than $\sigma_{8,m}$, which is the measured (non-linear) σ_8 of the particle density field.

The fitted values of β_h/f , however, are lower than unity, as expected. The results for β^* are plotted in Fig. 3, showing that the mass-weighted determination is nearly unbiased: at the fiducial $R_G = 4 h^{-1}$ Mpc, the MDPL2 field has $\beta^* = 1.05$, whereas for Bolshoi $\beta^* = 1.02$. This suggests that linear biasing correction works well, even for fields with $b_h \sim 1.7$. The 1D σ_v ($\sim 160 \text{ km s}^{-1}$) is only marginally higher than when particles were used for the density field.

5.3 Discussion: cross-correlation and optimal smoothing

It is not obvious why a Gaussian smoothing, with $R_G \sim 3$ to $4 h^{-1}$ Mpc, should be the ‘correct’ smoothing length. We can gain some insight by considering the problem in Fourier space, specifically equation (4) that relates the velocity modes to the density modes in linear perturbation theory. This should be exact on large scales, but we expect it to break down at high k .

For simplicity, first assume that all Fourier modes are Gaussian and independent and that at a given k the joint distribution of velocity and density mode amplitudes is given by a bivariate Gaussian. We expect the correlation coefficient, ρ , to approach 1 on large scales and zero at high k . Generally if one has a bivariate normal distribution of two variables x and y , and one regresses y on x , the slope of the relation is $\rho \frac{\sigma_y}{\sigma_x}$, or since the covariance $C_{xy} = \rho \sigma_x \sigma_y$, the slope can also be written as C_{xy}/σ_x^2 . Therefore, the predicted velocity mode

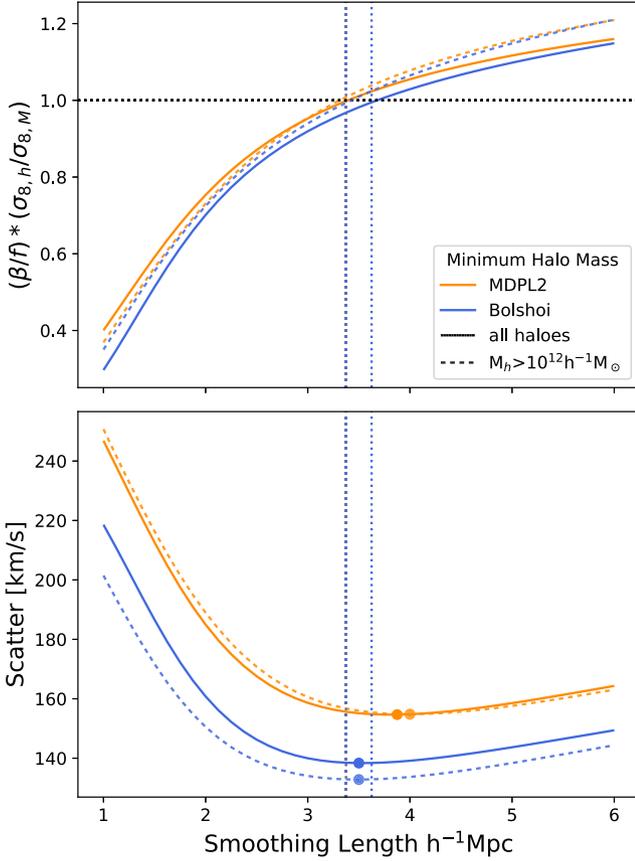


Figure 3. Similar to Fig. 2, except here the mass-weighted halo density field is used to predict peculiar velocities of haloes. The vertical axis in the top panel is now $\beta/f(\sigma_{8,h}/\sigma_{8,m})$.

amplitude is given by the density mode amplitude times the slope $C_{v\delta}/\sigma_\delta^2$.

The quantities $C_{v\delta}$ and σ_δ^2 can be measured in N -body simulations as a function of wavenumber k . The latter is just the power spectrum of matter density fluctuations, $P_{\delta\delta}$, but the covariance is less well studied. Zheng et al. (2013) have measured the cross-spectrum of the closely related quantity $\theta = \nabla \cdot v$ with the density δ , and its ratio with the density power spectrum. They define the normalized window function

$$\tilde{W}_k = \frac{1}{f} \frac{P_{\theta\delta}}{P_{\delta\delta}}, \quad (14)$$

which has the property that it asymptotes to 1 at low k and goes to zero at higher k . This function is plotted in Fig. 4. Also overplotted for comparison are two Gaussian smoothing filters with $R_G = 2.88$ and $4.0 h^{-1}$ Mpc. The estimated β/f from the particle-weighted density field smoothed using either \tilde{W}_k as a k -space smoothing function or with a Gaussian kernel of $R_G = 2.88 h^{-1}$ Mpc both produce values of 0.88. There is also no significant difference in σ_v .

The Gaussian smoothing with $R_G = 4.0 h^{-1}$ Mpc is a better match to \tilde{W}_k at low k .

In reality, particularly at high k , the assumption of bivariate Gaussianity will no longer be correct, so the above simple argument will break down. In principle, with detailed knowledge of the correlations, it should be possible to design the optimal k -space filter. For our purposes in this paper, we retain the simplicity of Gaussian smoothing, and adopt a Gaussian smoothing filter with $R_G = 4 h^{-1}$ Mpc for consistency with previous work.

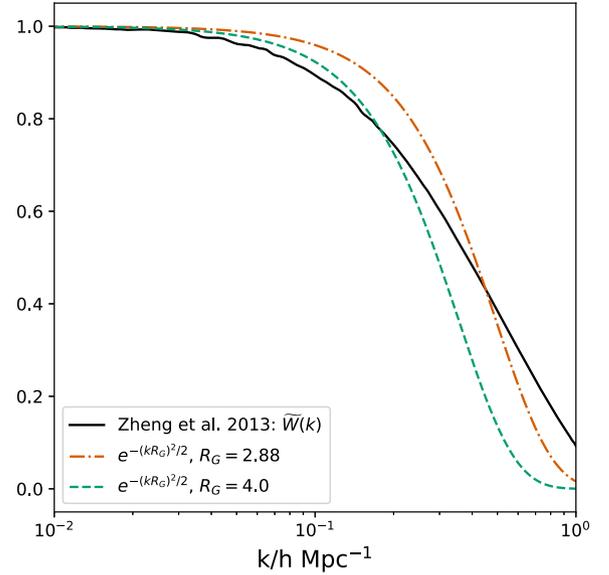


Figure 4. The normalized window function from Zheng et al. (2013), calculated from the J1200 simulation, based on the correlation of the velocity and density fields (see text for details) is shown, with Window functions for Gaussian smoothing kernels with scales of 2.85 and $4.0 h^{-1}$ Mpc. Both functions exhibit the expected characteristics of being unity as $k \rightarrow 0$ and zero as $k \rightarrow \infty$. \tilde{W}_k and the Gaussian kernel of $R_G = 2.88 h^{-1}$ Mpc cross 0.5 near $k = 0.39$ and $0.41 h^{-1}$ Mpc $^{-1}$, respectively.

6 THE EFFECT OF UNCERTAINTY IN THE HALO MASSES

In the previous sections, the masses of the haloes were assumed to be known exactly, with no uncertainty in the measurements. However, in real survey data there is some uncertainty in the true mass of any given halo, depending on the method used to estimate it, and this may be in the range 0.1–0.2 dex (see Section 7). In this section, we explore how scattering the halo mass impacts the predictions of β/f and $\sigma_{8,h}$. This is accomplished by varying the halo masses by a lognormal Gaussian random variable with standard deviations corresponding to 0.1 and 0.2 dex, and calculating σ_8 and β for each realization. A total of 500 realizations were performed on both the Bolshoi and MDPL2 halo catalogues.

We find that, from realization to realization, both the measured β and σ_8 deviate from the no-scatter values, and these deviations are anticorrelated. This can be understood as follows. In Section 5.3, we discussed how the slope (β) could be expressed as the ratio of the covariance between density and velocity, and the density power spectrum, $C_{v\delta}/\sigma_{\delta\delta}^2$. If noise is added to the density field, then the denominator increases, but the covariance is unaffected. Consequently, the fitted β drops. On the other hand, σ_8 increases because of the additional noise. This anticorrelation leads to some cancellation of the additional noise from realization to realization in the product $\beta^* = \beta_h \sigma_{8,h}$.

The net result of increasing the halo mass scatter and its impact on β^* are shown in the top panel of Fig. 5, with a scatter of zero dex corresponding to the case where the halo masses are precisely measured. We find that when introducing a lognormal scatter, the value of β^* increases only slightly with increasing scatter for both Bolshoi and MDPL2. We note, however, that the standard deviation of β^* is higher for Bolshoi due to the smaller volume of the simulation, which leads to greater variation from realization to realization in β_h , σ_h and their product β^* . For MDPL2, the net effect of scatter in

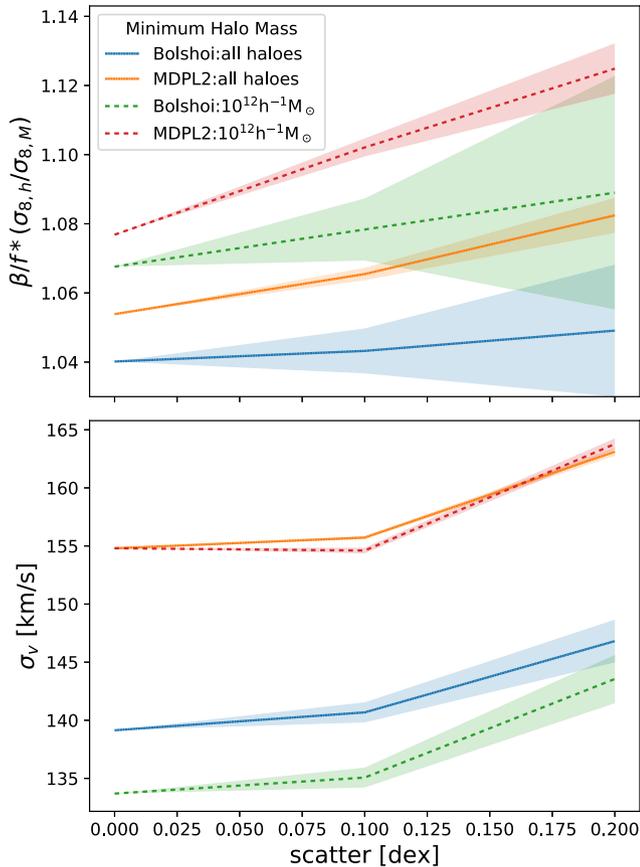


Figure 5. Effect of additional scatter to the mass of haloes as a function of the logarithmic scatter (0, 0.1, and 0.2 dex). For 0 dex, this is the measured value of the simulation, for 0.1 and 0.2 dex a random value corresponding to a lognormal Gaussian with a σ of ~ 0.23 and 0.5 , respectively, has been applied to each halo in the catalogue. Top panel: The mean (dark line) and $\pm 1\sigma$ range (shaded band) of these measurements are shown for $\beta/f(\sigma_{8,h}/\sigma_{8,m})$ at a smoothing radius of $4 h^{-1}$ Mpc. Bottom panel: scatter around the best fit of σ_v for the same smoothing.

the N independent halo masses is reduced by a factor $1/\sqrt{N}$ due to the larger volume containing a larger number (N) of haloes. This highlights the importance of the volume of the sample, a topic we shall discuss in greater detail in Section 8.

The bottom panel shows how the 1D σ_v is impacted by introducing stochasticity in the halo masses. We find that the 0.1 dex case generates a negligible change in the measured σ_v when compared to the original value. For halo mass uncertainties of 0.2 dex, σ_v increases, but the effect is still small, corresponding to $\sim 8 \text{ km s}^{-1}$.

7 GALAXIES AS TRACERS OF THE DENSITY FIELD

Galaxies trace the underlying DM distribution on large scales, but observable quantities, such as a galaxy’s luminosity and stellar mass, do not necessarily have an exact relationship with the mass of the halo in which a galaxy lies. To explore how using these quantities as a proxy for mass density impact β/f and σ_8 , we use two semi-analytical galaxy formation models available for the MDPL2 simulations SAG (Cora 2006) and SAGE (Croton et al. 2016).

Many DM haloes host more than one galaxy, which are typically divided into centrals (the galaxy identified with the main or host DM halo) and satellites (associated with DM subhaloes). When predicting

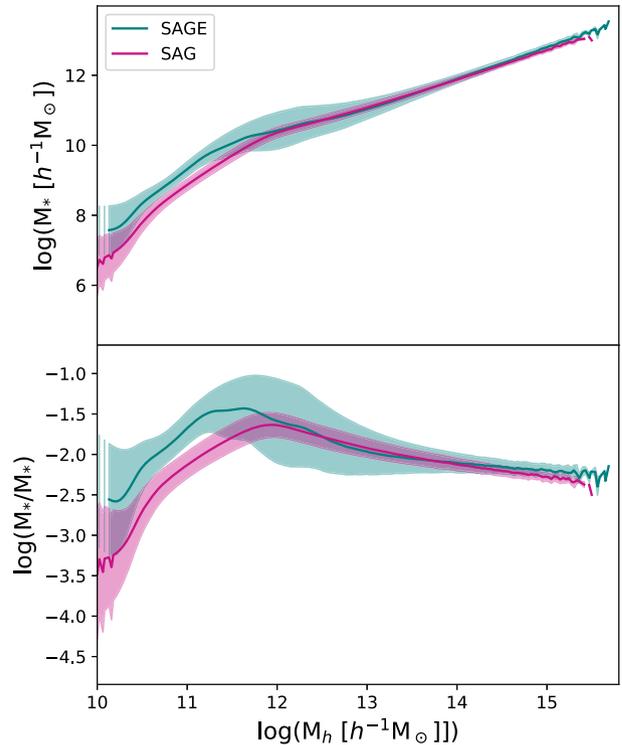


Figure 6. Top panel: The SHMR for the total stellar mass of a halo (including stellar mass in subhaloes) as a function of total halo mass. The dark curves show the means of the SHMR and the lighter bands indicate their measured standard deviation. Both SAG and SAGE semi-analytical models are shown. Bottom panel: the SHMR as a function of halo mass.

host halo mass, one can use only the stellar mass or luminosity of the central galaxy, or one can use the total stellar mass (or total luminosity) of all galaxies. We adopt the latter approach here when calculating the density fields. As before, velocity comparisons will be done solely on galaxies classified as centrals. For consistency with the previous work done in this paper, any cuts imposed on the data will be done using the mass of the host halo.

The SHMR is different for both the SAG and SAGE semi-analytical models in MDPL2, see Fig. 6. SAG has a tighter SHMR with less scatter in stellar mass at a given halo mass: for haloes with masses between 10^{11} and $10^{13} h^{-1} M_{\odot}$, it has an average scatter of 0.15 dex compared to 0.39 dex in SAGE. The average SHMR is comparable for both SAG and SAGE for halo masses greater than the characteristic pivot point at $\sim 10^{12} h^{-1} M_{\odot}$.

7.1 Predictions using stellar-to-halo mass relations

To construct a proxy mass density field, we can obtain proxy halo masses using the SHMR. The K -band luminosity is a good proxy for stellar mass, however, the galaxy luminosities in SAG are limited to the u, g, r, i, z bands. So in this section, we use the stellar masses provided for both SAG and SAGE. We fit the SHMR profiles of both SAG and SAGE semi-analytical models with a broken power law, and use these to convert the stellar masses into halo masses. Then the same analysis described in a previous section is performed. This procedure will remove the non-linearity of the SHMR relation, but cannot remove the scatter in it, since the mean SHMR is used for each halo.

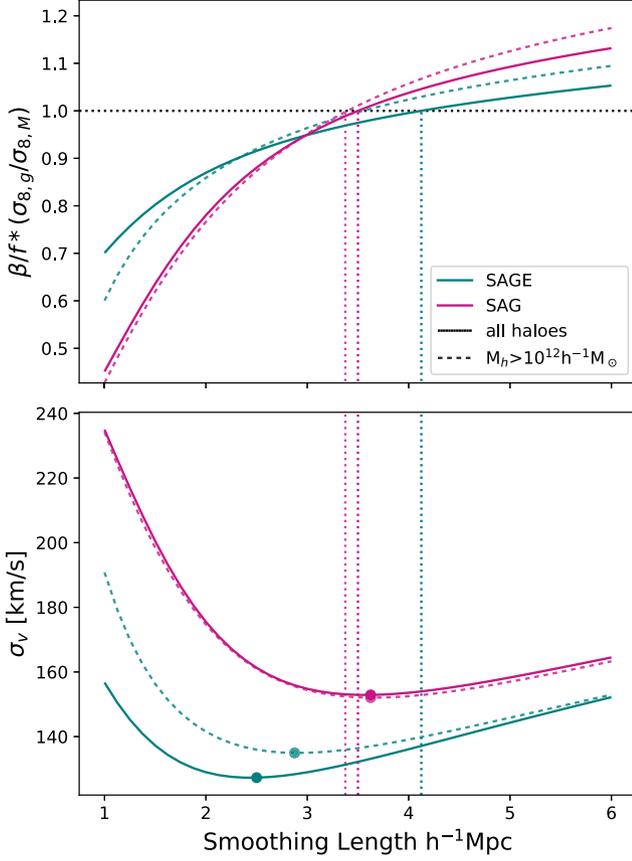


Figure 7. Similar to Fig. 3, except here a fitted SHMR is used to predict the halo masses from stellar masses, and then constructing a mass-weighted halo density field to predict the peculiar velocities of central galaxies.

From Fig. 7, we find for the SAGE galaxies, β^* is unbiased for a Gaussian smoothing of $4.1 h^{-1}$ Mpc but generates the lowest σ_v at $R_G = 2.6 h^{-1}$ Mpc. For SAG, these are at smoothing lengths of 3.6 and $3.5 h^{-1}$ Mpc, respectively. Comparing these results to Fig. 3, we find that at $R_G = 4 h^{-1}$ Mpc, SAG produces results that are quite similar (within a few per cent) to what was found using MDPL2’s halo masses directly. SAGE, however, generates values of β^* that are 5 per cent smaller at the same smoothing length than the haloes. We find that the generated SAG haloes produce similar estimates for the 1D scatter in velocity predictions, contrarily the SAGE haloes generate $\sim 20 \text{ km s}^{-1}$ less scatter.

Comparing these results to those in the next section, we note that while the halo mass does tend to be unbiased at smaller R_G the conversion of stellar to halo mass introduces $10\text{--}20 \text{ km s}^{-1}$ of additional scatter than using galaxy observables to predicted velocities.

We attribute the results to the differences in the models’ SHMR as a function of halo mass. SAG has a flatter SHMR than SAGE, and therefore it is close to the simple halo mass weighted case. SAGE has a steeper ratio at high halo masses, hence SAGE puts less weight on massive clusters leading to estimates of β^* slightly less than unity.

7.2 Predictions using galaxy observables

A density field can also be constructed without approximating the mass of individual haloes via the SHMR. In this section, we investigate how weighing directly by the galaxy observables impacts

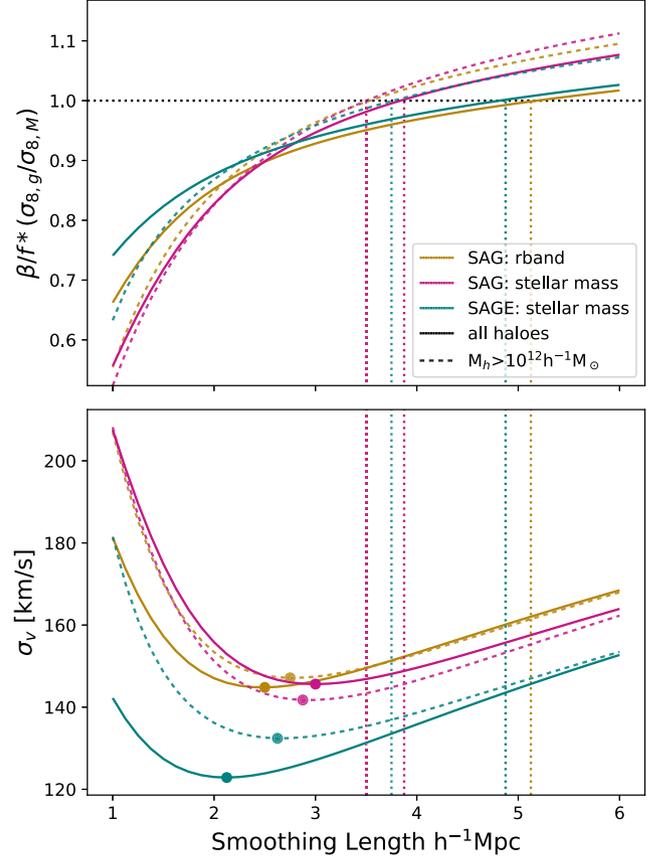


Figure 8. Similar to Fig. 7 except now the density field is constructed using galaxy observables (i.e. weighed by stellar mass or luminosity) to predict and measure centrals’ peculiar velocities.

the cosmological estimates. Such a procedure is closer to what was done by Carrick et al. (2015), who used the K -band luminosity-weighted density field from the 2M++ catalogue. Fig. 8 shows the summary of results discussed below.

We find that, for the SAG model, weighing the density field by stellar mass produces results that yield a higher β^* than luminosity weighting. We can weigh the density field using luminosities in any of the five bands provided by SAG. In the remainder of this paper, we focus on the r -band luminosity. We note, however, that the longest wavelength z band produces the highest values of β/f , however, after applying the correction factor $(\sigma_{8,g}/\sigma_{8,m})$ there is virtually no difference between bands for β^* , provided a low minimum mass threshold.

If the minimum mass threshold of the haloes is low, we find that weighing using the stellar masses provided by SAG closely resembles the case where the density field is halo mass weighted and is unbiased at an $R_G \sim 3.8 h^{-1}$ Mpc. The SAGE stellar mass and SAG r band predict β^* values that are comparable at $R_G > 3 h^{-1}$ Mpc, but only produce unbiased estimated of β^* for a Gaussian smoothing radius of $\sim 5 h^{-1}$ Mpc.

In the case where a minimum mass threshold of $10^{12} h^{-1} M_\odot$ is applied to the data, we find that β^* for the three cases are comparable for $3 h^{-1} \text{ Mpc} \lesssim R_G \lesssim 4 h^{-1} \text{ Mpc}$. With all the cases estimating unbiased β^* values at $3.5\text{--}3.7 h^{-1}$ Mpc. The σ_v is also comparable for these cases with the SAGE stellar mass producing only $\sim 10 \text{ km s}^{-1}$ less scatter than the SAG r band.

8 FINITE VOLUME AND COSMIC VARIANCE EFFECTS

In real data sets, both the data used to obtain the density field, based on redshift surveys, and the peculiar velocity samples, cover limited volumes. This has multiple consequences. Some of these are related to sample variance: the local volume will have local values of the mean density and of σ_8 that are different from the global values. Moreover, the predicted peculiar velocities will be less accurate for galaxies close to the edge of the density field than for those far from the edges, say at the centre of the volume.

In this section, we investigate these finite volume and edge effects by limiting the data, to spheres of radii with $R_{\max} = 50, 100, 150, 200,$ and $300 h^{-1}$ Mpc, and its impact on cosmological estimates. In particular, we are interested in simulations of data sets with $R_{\max} \sim 150 h^{-1}$ Mpc, which is comparable to the survey size of 2M++, the depth of which varies from 125 to 200 h^{-1} Mpc, with an effective spherically averaged radius of 175 h^{-1} Mpc. Given the size of the MDPL2 simulation, it is possible to generate multiple independent (non-overlapping) finite volume realizations. For each sphere, we ignore any galaxy that exists outside of the sphere, and assign $\delta = 0$ for points outside the sphere. Hence each sphere represents a local universe realization: it can be over- or underdense, so we renormalize δ using the mean density within the sphere instead of the simulation box average. For each sphere, we then calculate βf and $\sigma_{8,g}$ using only that sphere's galaxies, although $\sigma_{8,m}$, which appears in the denominator of β^* , continues to be calculated from the full simulation. As in real analyses, to account for the missing contribution from structures beyond the sphere's edge, in addition to fitting the βf , we also fit a residual bulk flow term.

Fig. 9 demonstrates how β^* and $\sigma_{8,g}$ depend on R_{\max} for the case with no mass cut on the galaxy catalogue. As expected, as the size of the sphere increases, results converge to the values found for the full simulation for $R_{\max} \geq 200 h^{-1}$ Mpc.

There is a significant amount of scatter in the measured σ_8 values for small R_{\max} , varying by as much as 10 per cent of the mean value, and with a mean value that tends to be between 4 and 8 per cent lower than that of the full simulation. The bias in the mean may be due to renormalizing the density fluctuation, $\delta = (\rho - \bar{\rho})/\bar{\rho}$ with the local $\bar{\rho}$ measured on the scale of the sphere, R_{\max} , thus effectively filtering out the contribution to σ_8 from large-scale waves. The scatter arises from sample variance effects, which is a combination of cosmic variance in the underlying DM structures and stochasticity in the SHMR. This decreases as R_{\max} increases.

Likewise, the locally measured value of βf also varies from sphere to sphere. Again, there are several reasons for this. First, the local $\bar{\rho}$ averaged over the sphere will differ from the true average. This is important because, as noted above, it leads to a renormalization of δ . Second, there is also stochasticity in the SHMR that may affect the locally measured βf . Of these two, the first effect is the dominant one: we find that the total scatter in βf for $R_{\max} = 150 h^{-1}$ Mpc at $R_G = 4 h^{-1}$ Mpc is typically 7.0 per cent and is mostly due to cosmic variance in $\bar{\rho}$. The scatter in βf dominates the scatter in $\sigma_{8,g}$ (2.5 per cent) when they are combined in β^* .

Fig. 10 demonstrates how the cut samples ($R_{\max} = 150 h^{-1}$ Mpc) depend on the Gaussian smoothing radius R_G . In particular, when compared to Fig. 8 we find that the average β^* for these volume-limited realizations is unbiased between 3.75 and 4.75 h^{-1} Mpc. The value of β^* at $R_G = 4 h^{-1}$ Mpc ranges between 0.98 and 1.01. More importantly, the standard deviation in β^* from sphere to sphere is 0.077 at $R_{\max} = 150 h^{-1}$ Mpc, although this declines significantly to 0.032 at 200 h^{-1} Mpc and 0.020 at 300 h^{-1} Mpc. This suggests

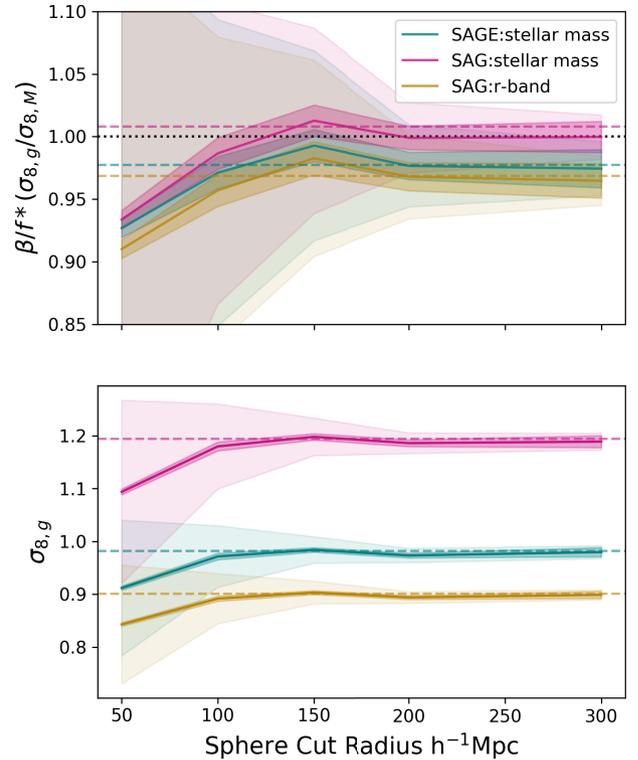


Figure 9. To demonstrate the dependence of our calculated parameters on the survey volume, we restrict simulation data to (non-overlapping) spheres of radius ranging from 50 to 300 h^{-1} Mpc. The components of β^* are calculated for each test sample assuming a Gaussian smoothing kernel of 4 h^{-1} Mpc. The upper panel and lower panel show the results for β^* and in σ_8 measurements, respectively, as a function of sphere radius. In both panels, the light and dark coloured bands represent the $\pm 1\sigma$ standard deviation from sphere to sphere and the standard error in the mean of the test cases (respectively) for a given sample spherical radius, with the mean being shown by the solid colour lines. The colour horizontal dashed lines show the values from the full simulation box.

that sample variance effects are the dominant uncertainty in $f\sigma_8$ for current data sets.

The 1D velocity scatter as a function of R_G has a similar shape as found previously, but is 40–50 km s^{-1} larger than for the full simulation box. This increase in the scatter is primarily due to the degradation of the predicted velocities as one approaches R_{\max} . When we compare the 1D σ_v for the subsample of galaxies located within the inner half of the sphere's volume with those in the outer half at an $R_G = 4 h^{-1}$ Mpc, we find scatters of ~ 165 and $\sim 210 \text{ km s}^{-1}$, respectively. This increase is attributed to the fact that the velocity tracers near the outer edge have poorer predicted peculiar velocities because of unaccounted-for structures outside of the survey limits.

9 SUMMARY AND DISCUSSION

The key results of this paper are as follows:

- (i) The velocities of DM haloes are well predicted by linear theory from the true density field with a Gaussian smoothing $R_G = 4 h^{-1}$ Mpc with a velocity scatter of 154 km s^{-1} . This is in agreement with appendix A of Carrick et al. (2015).
- (ii) This can be understood because, in Fourier space, a Gaussian filter with $R_G = 3\text{--}4 h^{-1}$ Mpc is a good match to the cross-correlation function of the density and velocity fields.

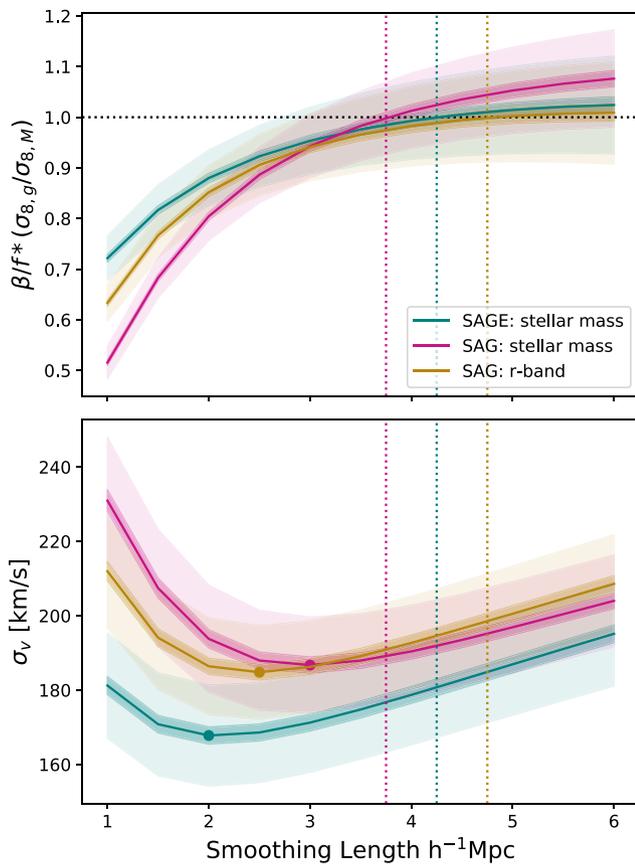


Figure 10. Similar to Fig. 8 expect we now use non-overlapping sphere cuts of radius $150 h^{-1}$ Mpc and the components of β^* are calculated for a range of Gaussian kernel lengths between 1 and $6 h^{-1}$ Mpc. The bands have the same meaning as in Fig. 9.

Table 1. Summary of β^* values taken for $R_G = 4 h^{-1}$ Mpc for the various MDPL2 tracers that weigh the density field and from which the peculiar velocities are compared.

Density tracer	All M_t	$M_t > 10^{12} h^{-1} M_\odot$	
Particles	0.97	–	Fig. 1
Haloes	1.05	1.08	Fig. 3
SAGE: SHMR	1.00	1.02	Fig. 7
SAG: SHMR	1.04	1.06	Fig. 7
SAGE: stellar mass	0.98	1.01	Fig. 8
SAG: stellar mass	1.01	1.03	Fig. 8
SAG: r -band luminosity	0.97	1.02	Fig. 8

(iii) The accuracy and precision of the linear theory predictions do not depend on the mass of the velocity tracer; there is no ‘velocity bias’, except for clusters with $M_h > 10^{14} h^{-1} M_\odot$.

(iv) If DM haloes are used as tracers of the density field, and one calculates $\sigma_{8,h}$ of the halo mass weighted density field, then $\beta_h \sigma_{8,h}$ is a good estimator of $f\sigma_8$.

(v) If noise is added to the DM halo masses, then β^* is biased high by only a per cent, for a 0.1 dex noise level.

(vi) When galaxy luminosity or stellar mass are used for the density field, the values of β^* indicate that the method is unbiased to within 5 per cent, depending on the semi-analytical galaxy formation model.

(vii) When the density field is restricted to a finite volume, there is additional uncertainty due to cosmic variance, at the level of 7 per cent for a $150 h^{-1}$ Mpc sphere.

The results for β^* calculated using the same tracers for the velocity and density field, are summarized in Table 1. Overall we find that the method has ~ 5 per cent systematic uncertainties. This can be improved with semi-analytical galaxy formation models that more carefully match the real SHMR and its scatter. There is also uncertainty due to finite volumes and cosmic variance.

Previous work has neglected the additional scatter due to the coupled effects of stochasticity in the galaxy–mass relation and the cosmic variance effect of finite volumes. For example, the 2M++ catalogue (Lavaux & Hudson 2011) has an effective volume of $175 h^{-1}$ Mpc. The SAGE model, weighed by stellar mass, shows that, for $150 h^{-1}$ Mpc spheres, the uncertainty on $\beta_g \sigma_{8,g} = f\sigma_8$ is 7.7 per cent, while the expected (interpolated) value for a survey of 2M++’s size is 5.2 per cent. This is slightly higher than the uncertainty estimated by Carrick et al. (2015), Boruah et al. (2020), and Said et al. (2020) who adopted a 4 per cent sampling variance uncertainty, plus observational errors in β due to uncertainties in peculiar velocity measurements, which are subdominant. For precise quantification of the biases and systematic uncertainties in $f\sigma_8$ derived from a specific survey, e.g. 2M++, the best approach to minimizing the systematic errors will be to create mock catalogues that mimic the geometry and selection of that particular survey.

The cosmic variance uncertainty can be reduced in the future with deeper, all-sky redshift surveys. For example, a survey extending to a redshift of 0.2 ($600 h^{-1}$ Mpc) would have an uncertainty of only 0.4 per cent in the mean mass density and hence 0.5–0.6 per cent in the luminosity (or stellar mass) density. In the North, the DESI Bright Galaxy Survey (DESI Collaboration 2016), will observe 10 million nearby galaxies. In the South, 4MOST (de Jong et al. 2019) has the capability to survey large volumes in the nearby Universe. The future looks bright.

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DATA AVAILABILITY STATEMENT

The data underlying this article are publicly available from the COSMOSIM data base <https://www.cosmosim.org/>, with their respective publications cited in Section 3.

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